

FULL STABILITY OF VARIATIONAL SYSTEMS

BORIS MORDUKHOVICH

Wayne State University

Detroit, MI 48202, USA

Talk given at the **TERRY FEST**

based on joint work with **Tran Nghia**

TRIBUTE TO TERRY ROCKAFELLAR

Limoges, France, May 2015

Supported by NSF grant DMS-1007132

PARAMETRIC VARIATIONAL SYSTEMS (PVS)

given in the following form

$$v \in f(x, p) + \partial_x g(x, p)$$

where $x \in X$ is the **decision** variable from a **Hilbert** space X , $v \in X$ signifies **canonical** perturbations while $p \in P$ **basic** ones from a metric space P , f is **smooth** around (\bar{x}, \bar{p}) , g is **extended-real-valued l.s.c.**, ∂_x stands for the **partial limiting subdifferential**

Solution map to (PVS) is

$$S(v, p) := \left\{ x \in X \mid v \in f(x, p) + \partial_x g(x, p) \right\}$$

FULL STABILITY OF LOCAL MINIMIZERS

We say that \bar{x} is a Lipschitzian fully stable local minimizer of $g: X \times P \rightarrow \overline{\mathbb{R}}$ relative to $\bar{p} \in P$ if there exist $\kappa, \ell, \gamma > 0$ and a ngbh $V \times Q$ of (\bar{v}, \bar{p}) such that the argminimum mapping

$$(v, p) \mapsto M_\gamma(v, p) := \operatorname{argmin} \left\{ g(x, p) - \langle v, x \rangle \mid \|x - \bar{x}\| \leq \gamma \right\}$$

is single-valued on $V \times Q$ with $M_\gamma(\bar{v}, \bar{p}) = \bar{x}$, satisfying

$$\|M_\gamma(v_1, p_1) - M_\gamma(v_2, p_2)\| \leq \kappa \|v_1 - v_2\| + \ell d(p_1, p_2)$$

and in addition the local value function

$$(v, p) \mapsto m_\gamma(v, p) := \inf \left\{ g(x, p) - \langle v, x \rangle \mid \|x - \bar{x}\| \leq \gamma \right\}$$

is also locally Lipschitz continuous around (\bar{v}, \bar{p}) .

The Hölder full stability postulates

$$\|M_\gamma(v_1, p_1) - M_\gamma(v_2, p_2)\| \leq \kappa \|v_1 - v_2\| + \ell d(p_1, p_2)^{\frac{1}{2}}$$

LOCAL MONOTONICITY

DEFINITION Let $T: X \rightrightarrows X$ be a set-valued operator in a Hilbert space, and let $(\bar{x}, \bar{v}) \in \text{gph } T$. We say that

(i) T is **locally strongly monotone** around (\bar{x}, \bar{v}) with **modulus** $\kappa > 0$ if there is a neighborhood $U \times V$ of (\bar{x}, \bar{v}) such that

$$\langle v_1 - v_2, u_1 - u_2 \rangle \geq \kappa \|u_1 - u_2\|^2, \quad (u_1, v_1), (u_2, v_2) \in \text{gph } T \cap (U \times V)$$

(ii) T is **locally strongly maximal monotone** around (\bar{x}, \bar{v}) with **modulus** $\kappa > 0$ if there is a neighborhood $U \times V$ such that the above inequality holds and that $\text{gph } T \cap (U \times V) = \text{gph } S \cap (U \times V)$ for any monotone operator S with $\text{gph } T \cap (U \times V) \subset \text{gph } S$

(iii) T is locally hypomonotone around (\bar{x}, \bar{v}) if there is a neighborhood $U \times V$ of this point and $r > 0$ such that

$$\langle v_1 - v_2, u_1 - u_2 \rangle \geq -r \|u_1 - u_2\|^2, \quad (u_1, v_1), (u_2, v_2) \in \text{gph } T \cap (U \times V)$$

STRONG MONOTONICITY VIA LOCALIZATION

THEOREM For $T : X \rightrightarrows X$ in Hilbert spaces the following assertions are equivalent

(i) T is **locally strongly maximally monotone** around $(\bar{x}, \bar{v}) \in \text{gph } T$ with modulus $\kappa > 0$

(ii) T is **locally strongly monotone** around (\bar{x}, \bar{v}) with modulus κ and the inverse mapping T^{-1} admits a **Lipschitz continuous single-valued localization** around (\bar{v}, \bar{x})

(iii) The mapping T^{-1} admits a **single-valued localization** ϑ relative to a neighborhood $V \times U$ of (\bar{v}, \bar{x}) such that for all $v_1, v_2 \in V$ we have the estimate

$$\left\| (v_1 - v_2) - 2\kappa [\vartheta(v_1) - \vartheta(v_2)] \right\| \leq \|v_1 - v_2\|$$

CODERIVATIVES

Given $T: X \rightrightarrows X$ and $(\bar{x}, \bar{y}) \in \text{gph } T$, the **regular coderivative** of T at (\bar{x}, \bar{y}) is defined by

$$\widehat{D}^*T(\bar{x}, \bar{y})(u) := \left\{ v \in X \mid \limsup_{\substack{(x,y) \rightarrow (\bar{x}, \bar{y}) \\ y \in T(x)}} \frac{\langle u, x - \bar{x} \rangle - \langle v, y - \bar{y} \rangle}{\|x - \bar{x}\| + \|y - \bar{y}\|} \leq 0 \right\}$$

The **limiting coderivative** of T at (\bar{x}, \bar{y}) is

$$D^*T(\bar{x}, \bar{y})(\bar{u}) := \left\{ \bar{v} \mid \exists (x_k, y_k, u_k, v_k) \rightarrow (\bar{x}, \bar{y}, \bar{u}, \bar{v}), v_k \in \widehat{D}^*T(x_k, y_k)(u_k) \right\}$$

The limiting coderivative D^*T enjoys **full pointwise calculus**

NGBH CHARACT. OF LOCAL STRONG MAX MONOTONICITY

THEOREM Let $T: X \rightrightarrows X$ be of closed graph around the point $(\bar{x}, \bar{v}) \in \text{gph } T$. The following are **equivalent**

(i) T is **locally strongly maximal monotone** around (\bar{x}, \bar{v}) with modulus $\kappa > 0$

(ii) T is **locally hypomonotone** around (\bar{x}, \bar{v}) and there is $\eta > 0$ such that

$$\langle z, w \rangle \geq \kappa \|w\|^2 \text{ for all } z \in \widehat{D}^*T(u, v)(w), (u, v) \in \text{gph } T \cap B_\eta(\bar{x}, \bar{v})$$

The conditions in (ii) ensure the **strong metric regularity** of T around (\bar{x}, \bar{v}) with modulus κ^{-1}

POINT. CHARACT. OF LOCAL STRONG MAX MONOTON.

THEOREM Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be Lipschitz continuous around \bar{x} . The following are equivalent

(i) T is locally strongly monotone around $(\bar{x}, T(\bar{x}))$ with some modulus $\kappa > 0$

(ii) $D^*T(\bar{x})$ is positive-definite in the sense that

$$\langle z, w \rangle > 0 \text{ whenever } z \in D^*T(\bar{x})(w), w \neq 0$$

LIPSCHITZ AND HÖLDER FULL STABILITY OF PVS

DEFINITION (i) \bar{x} is a **Lipschitzian fully stable** solution to PVS for the parameter pair (\bar{v}, \bar{p}) if the solution map admits a single-valued localization ϑ relative to some neighborhood $V \times Q \times U$ of $(\bar{v}, \bar{p}, \bar{x})$ such that for any $(v_1, p_1), (v_2, p_2) \in V \times Q$ we have

$$\left\| (v_1 - v_2) - 2\kappa [\vartheta(v_1, p_1) - \vartheta(v_2, p_2)] \right\| \leq \|v_1 - v_2\| + \ell d(p_1, p_2)$$

with some positive constants κ and ℓ

(ii) \bar{x} is a **Hölderian fully stable** solution to PVS if

$$\left\| (v_1 - v_2) - 2\kappa [\vartheta(v_1, p_1) - \vartheta(v_2, p_2)] \right\| \leq \|v_1 - v_2\| + \ell d(p_1, p_2)^{\frac{1}{2}}$$

with some positive constants κ and ℓ

SUBDIFFERENTIALS

for $g: X \rightarrow (-\infty, \infty]$ with $\bar{x} \in \text{dom } g$, $E_g(x) = \{\alpha \in \mathbb{R} \mid \alpha \geq g(x)\}$

regular

$$\hat{\partial}g(\bar{x}) = \widehat{D}^* E_g(\bar{x}, g(\bar{x}))(1)$$

limiting

$$\partial g(\bar{x}) = D^* E_g(\bar{x}, g(\bar{x}))(1)$$

singular/horizon

$$\partial^\infty g(\bar{x}) = D^* E_g(\bar{x}, g(\bar{x}))(0)$$

STANDING ASSUMPTIONS FOR FULL STABILITY

(A1) f is smooth in x around (\bar{x}, \bar{p}) uniformly in p and

$$\|f(x, p_1) - f(x, p_2)\| \leq Ld(p_1, p_2), \quad x \in U, p_1, p_2 \in Q$$

(A2) g is parametrically continuously prox-regular at (\bar{x}, \bar{p}) for $\hat{v} = \bar{v} - f(\bar{x}, \bar{p}) \in \partial_x g(\bar{x}, \bar{p})$

(A3) The following basic constraint qualification (BCQ) holds

$$(0, q) \in \partial^\infty g(\bar{x}, \bar{p}) \implies q = 0$$

2nd-ORDER CHARACT. OF HÖLDER FULL STABILITY

THEOREM Let (A1)–(A3) hold in Hilbert spaces. Then the following are **equivalent**

(i) \bar{x} is a **Hölderian fully stable solution** of PVS corresponding to the parameter pair (\bar{v}, \bar{p}) with the moduli $\kappa, \ell > 0$

(ii) There exists a number $\eta > 0$ such that whenever $(u, p, v) \in \text{gph } \partial_x g \cap \mathbb{B}_\eta(\bar{x}, \bar{p}, \bar{v})$ we have

$$\langle \nabla_x f(\bar{x}, \bar{p})w, w \rangle + \langle z, w \rangle \geq \kappa \|w\|^2 \quad \text{for } z \in (\widehat{D}^* \partial g_p)(u, v)(w), w \in X$$

where $g_p(x) = g(x, p)$

2nd-ORDER CHARACT. OF LIPSCHITZ FULL STABILITY

THEOREM Under the validity of (A1)–(A3) in finite dimensions the Lipschitzian full stability of $\bar{x} \in S(\bar{v}, \bar{p})$ for PVS with some modulus $\kappa > 0$ is equivalent to the simultaneous validity of the following pointwise conditions

$$\langle \nabla_x f(\bar{x}, \bar{p})w, w \rangle + \langle z, w \rangle > 0 \text{ for all } (z, q) \in (D^* \partial_x g)(\bar{x}, \bar{p}, \hat{v})(w), w \neq 0$$

$$(0, q) \in (D^* \partial_x g)(\bar{x}, \bar{p}, \hat{v})(0) \implies q = 0$$

REFERENCES

1. **R. A. POLIQUIN** and **R. T. ROCKAFELLAR**, Tilt stability of a local minimum, [SIAM J. Optim.](#) 8 (1998), 287–299
2. **R. T. ROCKAFELLAR** and **R. J-B WETS**, [Variational Analysis](#), Springer, 1998
3. **B. S. MORDUKHOVICH**, [Variational Analysis and Generalized Differentiation, I: Basic Theory](#) , Springer, 2006
4. **B. S. MORDUKHOVICH**, **T. T. A. NGHIA** and **R. T. ROCKAFELLAR**, Full stability in finite-dimensional optimization, [Math. Oper. Res.](#) 40 (2015), 226–252

5. **B. S. MORDUKHOVICH** and **T. T. A. NGHIA**, Local strong maximal monotonicity and full stability for parametric variational systems, to appear in [Trans. Amer. Math. Soc.](#)