

Duality and optimality in stochastic optimization and mathematical finance

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Conjugate duality

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Conjugate duality studies parametric optimization problems

$$\text{minimize } F(x, u) \quad \text{over } x \in X, \quad (\text{P})$$

where the parameter u takes values in a locally convex space U in separating duality with Y . If F is convex on $X \times U$, then

- the optimum value $\varphi(u)$ is convex on U ,
- the associated Lagrangian

$$L(x, y) = \inf_{u \in U} \{F(x, u) - \langle u, y \rangle\}.$$

is convex concave on $X \times Y$,

- the conjugate of φ can be expressed as

$$\varphi^*(y) = \sup_{u \in U} \{\langle u, y \rangle - \varphi(u)\} = - \inf_{x \in X} L(x, y).$$

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- If φ is **closed**, then there is no duality gap: $\varphi = \varphi^{**}$.
- If φ is **subdifferentiable** at u , then $x \in X$ solves (P) if and only if (x, y) is a **saddle point** of $L - \langle \cdot, y \rangle$ for some $y \in Y$.

Note that we have **not** assumed that X is locally convex.

- In **stochastic optimization**, this will allow us to choose a large enough X so that primal solutions exist and φ is closed.
- On the other hand, we will have to work a bit harder to find explicit expressions for φ^* and the saddle point conditions.

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Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t=0}^T, P)$ be a filtered probability space and consider the parametric optimization problem

minimize $E f(x, u) := \int f(x(\omega), u(\omega), \omega) dP(\omega)$ over $x \in \mathcal{N}$,

- $\mathcal{N} = \{(x_t)_{t=0}^T \mid x_t \in L^0(\Omega, \mathcal{F}_t, P; \mathbb{R}^d)\}$,
- $u \in L^p(\Omega, \mathcal{F}, P; \mathbb{R}^m)$ is a fixed parameter,
- $f : \mathbb{R}^{d(T+1)} \times \mathbb{R}^m \times \Omega \rightarrow \overline{\mathbb{R}}$ is a **convex normal integrand**,
- the integral is defined as $+\infty$ unless the positive part of the integrand is integrable.

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Example 1 (Inequality constraints) *If*

$$f(x, u, \omega) = \begin{cases} f_0(x, \omega) & \text{if } f_j(x, \omega) + u_j \leq 0 \text{ for } j = 1, \dots, m, \\ +\infty & \text{otherwise,} \end{cases}$$

where f_j are convex normal integrands, then $\varphi(u)$ is the optimal value of the problem

$$\begin{aligned} & \underset{x \in \mathcal{N}}{\text{minimize}} && E f_0(x(\omega), \omega) \\ & \text{subject to} && f_j(x(\omega), \omega) + u_j(\omega) \leq 0 \quad j = 1, \dots, m. \end{aligned}$$

This was studied by [Rockafellar and Wets, 1978] in the case of bounded strategies.

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Example 2 (Shadow price of information) *If*

$m = d(T + 1)$ and

$$f(x, u, \omega) = h(x + u, \omega),$$

*where h is a convex normal integrand, then the problem becomes the **nonadapted perturbation***

$$\underset{x \in \mathcal{N}}{\text{minimize}} \quad Eh(x + u).$$

of the stochastic optimization problem

$$\underset{x \in \mathcal{N}}{\text{minimize}} \quad Eh(x).$$

This was studied in [Rockafellar and Wets, 1976].

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Example 3 (Optimal stopping) *If $d = m = 1$ and*

$$f(x, u, \omega) = \begin{cases} \sum_{t=0}^T x_t Z_t(\omega) & \text{if } x \geq 0 \text{ and } \sum_{t=0}^T x_t \leq u, \\ +\infty & \text{otherwise,} \end{cases}$$

for an adapted real-valued process Z , the problem becomes

$$\underset{x \in \mathcal{N}_+}{\text{minimize}} \quad E \sum_{t=0}^T x_t Z_t \quad \text{subject to} \quad \sum_{t=0}^T x_t \leq u \text{ } P\text{-a.s.}$$

*When $u = 1$, this is a convex relaxation of the **optimal stopping problem**. The relaxation does not affect the optimal value.*

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Example 4 (Optimal investment) *Let $m = 1$ and*

$$f(x, u, \omega) = v \left(u - \sum_{t=0}^{T-1} x_t \cdot \Delta s_{t+1}(\omega) \right)$$

where s is an adapted price process and $v : \mathbb{R} \rightarrow \overline{\mathbb{R}}$ is convex. The problem becomes

$$\underset{x \in \mathcal{N}}{\text{minimize}} \quad E v \left(u - \sum_{t=0}^{T-1} x_t \cdot \Delta s_{t+1} \right)$$

which is the problem of optimal investment with liability u .

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Example 5 (Optimal investment in illiquid markets) *Let*

$$f(x, u, \omega) = \begin{cases} \sum_{t=0}^T v_t(S_t(\Delta x_t, \omega) + u_t) & \text{if } x_t \in D_t(\omega), x_T = 0 \\ +\infty & \text{otherwise} \end{cases}$$

where

- $S_t : \mathbb{R}^d \times \Omega \rightarrow \mathbb{R}$ is such that $S_t(\cdot, \omega)$ are convex with $S_t(0, \omega) = 0$ and $S_t(x, \cdot)$ are \mathcal{F}_t -measurable,
- $\omega \mapsto D_t(\omega)$ is \mathcal{F}_t -measurable with $D_t(\omega)$ closed convex and $0 \in D_t(\omega)$,
- $v_t : \mathbb{R} \rightarrow \overline{\mathbb{R}}$ is convex.

The problem becomes

$$\underset{x \in \mathcal{N}_D}{\text{minimize}} \quad E \sum_{t=0}^T v_t(S_t(\Delta x_t) + u_t).$$

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We will apply conjugate duality with

$$F(x, u) = Ef(x, u),$$

$$X = \mathcal{N},$$

$$U = L^p(\Omega, \mathcal{F}, P; \mathbb{R}^m),$$

$$Y = L^q(\Omega, \mathcal{F}, P; \mathbb{R}^m),$$

$$\langle u, y \rangle = E(u \cdot y).$$

- Our first aim is to show that, one often has

$$\varphi^*(y) = - \inf_{x \in \mathcal{N}} L(x, y) = - \inf_{x \in \mathcal{N}^\infty} L(x, y)$$

where $\mathcal{N}^\infty := \mathcal{N} \cap L^\infty$.

- This yields explicit expressions for φ^* in many situations.

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Let

$$\tilde{\varphi}(u) = \inf_{x \in \mathcal{N}^\infty} E f(x, u),$$

$$\mathcal{N}^\perp = \{v \in L^1(\Omega, \mathcal{F}, P; \mathbb{R}^n) \mid E(x \cdot v) = 0 \ \forall x \in \mathcal{N}^\infty\},$$

$$l(x, y, \omega) = \inf_{u \in \mathbb{R}^m} \{f(x, u, \omega) - u \cdot y\}.$$

Theorem 1 *If $\text{dom } El(\cdot, y) \cap \mathcal{N}^\infty \subseteq \text{dom } \tilde{\varphi}$, then*

$$\tilde{\varphi}^*(y) = - \inf_{x \in \mathcal{N}^\infty} El(x, y).$$

If in addition, there exists $v \in \mathcal{N}^\perp$ with $\tilde{\varphi}^(y) = Ef^*(v, y)$, then*

$$\varphi^*(y) = \tilde{\varphi}^*(y).$$

Lemma 2 (Perkkiö, 2014) *If $x \in \mathcal{N}$, $v \in \mathcal{N}^\perp$ and $E[x \cdot v]^+ \in L^1$, then $E(x \cdot v) = 0$.*

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Example 6 (Inequality constraints) *In the model*

$$\begin{aligned} & \underset{x \in \mathcal{N}}{\text{minimize}} && E f_0(x(\omega), \omega) \\ & \text{subject to} && f_j(x(\omega), \omega) + u_j(\omega) \leq 0 \quad j = 1, \dots, m, \end{aligned}$$

the conditions of Theorem 1 hold provided $f_j(x, \omega) \in L^p$ for all $x \in \mathbb{R}^n$. This follows from the Mackey-continuity of $El(\cdot, y)$ on L^∞ , which in turn follows from Rockafellar, Integrals which are convex functionals II, 1971. We have

$$l(x, y, \omega) = \begin{cases} f_0(x, \omega) + \sum_{j=1}^m y_j f_j(x, \omega) & \text{if } y \geq 0, \\ -\infty & \text{otherwise} \end{cases}$$

but, in general, don't have explicit expressions for $\varphi^(y)$.*

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Example 7 (Shadow price of information) *When $f(x, u, \omega) = h(x + u, \omega)$, the conditions of Theorem 1 hold as soon as $Eh \cap L^p$. We get*

$$\varphi^*(y) = \begin{cases} Eh^*(y) & \text{if } E_t y_t = 0 \ \forall t, \\ \infty & \text{otherwise} \end{cases}$$

and, in particular,

$$\varphi^{**}(0) = \sup_{y \in \mathcal{N}^\perp} E[-h^*(y)] = \sup_{y \in \mathcal{N}^\perp} E \inf_{x \in \mathbb{R}^n} \{h(x) - x \cdot y\},$$

hence the name [shadow price of information](#); see [Rockafellar and Wets, 1976], [Back and Pliska, 1987] and [Davis, 1992]. This allows for MC much as in [Rogers, 2002].

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Example 8 (Optimal stopping) *The optimal value of the optimal stopping problem*

$$\text{maximize}_{x \in \mathcal{N}_+} E \sum_{t=0}^T x_t Z_t \quad \text{subject to} \quad \sum_{t=0}^T x_t \leq 1$$

equals that of

$$\text{minimize}_{y \in \mathcal{M}^\infty} y_0 \quad \text{subject to} \quad y \geq Z^+,$$

where \mathcal{M}^∞ is the set of bounded martingales and Z^+ is the positive part of Z .

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Example 9 (Optimal investment) Assume that, $\forall x \in \mathcal{N}^\infty$
 $\exists u \in L^p$ such that $EV(u - \sum_{t=0}^{T-1} x_t \cdot \Delta s_{t+1}) < \infty$, then

$$\varphi^{**}(u) = \sup_{y \in \mathcal{Q}} E[uy - V^*(y)],$$

where \mathcal{Q} is the set of positive multiples of *martingale densities*
 $y \in \mathcal{Y}$, i.e. densities dQ/dP of probability measures $Q \ll P$
under which the price process s is a martingale.

Closedness criteria

- The above expressions for φ^{**} provide dual representations of the optimal value φ provided φ is proper and **lower semicontinuous** (lsc), i.e.

$$\liminf_{\nu \rightarrow \infty} \varphi(u^\nu) \geq \varphi(u)$$

whenever $u^\nu \rightarrow u$ in L^p .

- The traditional “direct method” assumes that Ef is jointly lsc and $Ef(\cdot, u)$ is inf-compact uniformly in u .
- In financial models, the topological inf-compactness condition often fails but there is a more general measure theoretic counterpart that works well in \mathcal{N} .

Closedness criteria

Theorem 3 (Komlós) *If $(x^\nu)_{\nu=1}^\infty \subset L^0(\Omega, \mathcal{F}, P; \mathbb{R}^n)$ is almost surely bounded in the sense that*

$$\sup_{\nu} |x^\nu(\omega)| < \infty \quad P\text{-a.s.}$$

then there is a sequence of convex combinations $\bar{x}^\nu \in \text{co}\{x^\mu \mid \mu \geq \nu\}$ that converges almost surely in L^0 .

This yields the following infinite-dimensional version of Theorem 8.4 from [Convex Analysis](#).

Theorem 4 *Let $C : \Omega \rightrightarrows \mathbb{R}^n$ be closed convex-valued and \mathcal{F} -measurable. If $\{x \in \mathcal{N} \mid x \in C^\infty \text{ a.s.}\} = \{0\}$, then every sequence in $\{x \in \mathcal{N} \mid x \in C \text{ a.s.}\}$ is almost surely bounded.*

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Theorem 5 *Assume that f is bounded from below and that*

$$\{x \in \mathcal{N} \mid f^\infty(x(\omega), 0, \omega) \leq 0 \text{ a.s.}\}$$

is a linear space. Then

$$\varphi(u) = \inf_{x \in \mathcal{N}} E f(x, u)$$

is closed on L^p and the inf is attained for every $u \in L^p$.

The lower bound has been relaxed in [Perkkiö, 2014].

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Example 10 (Optimal stopping) *When*

$$f(x, u, \omega) = \begin{cases} -\sum_{t=0}^T x_t Z_t(\omega) & \text{if } x \geq 0 \text{ and } \sum_{t=0}^T x_t \leq u, \\ +\infty & \text{otherwise,} \end{cases}$$

we have $f^\infty = f$ and

$$\{x \in \mathcal{N} \mid f^\infty(x, 0) \leq 0 \text{ a.s.}\} = \{0\},$$

so the linearity condition is always satisfied.

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Example 11 (Shadow price of information) *When*

$$f(x, u, \omega) = h(x + u, \omega),$$

the linearity condition means that

$$\{x \in \mathcal{N} \mid h^\infty(x) \leq 0 \text{ -a.s.}\}$$

is linear.

Closedness criteria

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Example 12 (Optimal investment) *When*

$$f(x, u, \omega) = \begin{cases} v \left(u - \sum_{t=0}^{T-1} x_t \cdot \Delta S_{t+1}(\omega) \right) & \text{if } x_t \in D_t(\omega), \\ +\infty & \text{otherwise} \end{cases}$$

we get

$$f^\infty(x, u, \omega) = \begin{cases} v^\infty \left(u - \sum_{t=0}^{T-1} x_t \cdot \Delta S_{t+1}(\omega) \right) & \text{if } x_t \in D_t^\infty(\omega) \\ +\infty & \text{otherwise.} \end{cases}$$

*If v is nonconstant and $D_t(\omega) = \mathbb{R}^J$, the linearity condition becomes the **no-arbitrage** condition*

$$x \in \mathcal{N} : \sum x_t \cdot \Delta S_{t+1} \geq 0 \implies \sum x_t \cdot \Delta S_{t+1} = 0.$$

Example 13 *With transaction costs, we get the **robust no-arbitrage** condition introduced by [Schachermayer, 2004].*

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The linearity condition may hold even under arbitrage.

Example 14 *It holds if $S_t^\infty(x, \omega) > 0$ for $x \notin \mathbb{R}_-^J$.*

Example 15 *In [Çetin and Rogers, 2007] with*

$$S_t(x, \omega) = x^0 + s_t(\omega)\psi(x^1)$$

one has $S_t^\infty(x, \omega) = x^0 + s_t(\omega)\psi^\infty(x^1)$. When $\inf \psi' = 0$ and $\sup \psi' = \infty$ we have $\psi^\infty = \delta_{\mathbb{R}_-}$, so the condition in Example 14 holds.

Example 16 *If $S_t(\cdot, \omega) = s_t(\omega) \cdot x$ for a componentwise strictly positive price process s and $D_t^\infty(\omega) \subseteq \mathbb{R}_+^J$ (infinite short selling is prohibited) then linearity condition holds.*

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Theorem 6 *Assume that $\partial\varphi(u) \neq \emptyset$ and that for every $y \in \partial\varphi(u)$ there exists $v \in \mathcal{N}^\perp$ such that $\varphi^*(y) = Ef^*(v, y)$. Then an $x \in \mathcal{N}$ solves (P) if and only if it is feasible and there exist $y \in \mathcal{Y}$ and $v \in \mathcal{N}^\perp$ such that*

$$(v, y) \in \partial f(x, u)$$

P-almost surely, or equivalently, if

$$v \in \partial_x l(x, y) \quad \text{and} \quad u \in \partial_y [-l](x, y)$$

P-almost surely.

Optimality conditions

Example 17 *In the model with constraints, the optimality condition of Theorem 6 means that*

$$\begin{aligned} f_j(x) + u_j &\leq 0, \\ x &\in \operatorname{argmin}_{z \in \mathbb{R}^n} \left\{ f_0(z) + \sum_{j=1}^m y_j f_j(z) - z \cdot v \right\}, \\ y_j f_j(z) &= 0 \quad j = 1, \dots, m, \\ y_j &\geq 0 \end{aligned}$$

P -almost surely. [Rockafellar and Wets, 1978] give sufficient conditions for the existence of an optimal $x \in \mathcal{N}^\infty$ and the corresponding dual variables $y \in \mathcal{Y}$ and $v \in \mathcal{N}^\perp$.

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Example 18 Consider the optimal investment problem in liquid markets and assume that EV is finite on L^p and EV^* is proper in L^q . Then an $x \in \mathcal{N}$ solves (P) if and only if it is feasible and there exists a martingale density y for s such that

$$y \in \partial V\left(u - \sum_{t=0}^{T-1} x_t \cdot \Delta s_{t+1}\right) \quad P\text{-a.s.}$$

much like e.g. in [Schachermayer, 2001] or [Biagini and Frittelli, 2008] in continuous time.

Continuous-time models

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- Continuous time models of financial mathematics are often expressed in terms of the **stochastic integral** (wealth process) of the portfolio process wrt the price process.
- However, the definition of $(x, u) \mapsto Ef(x, u)$ relies on **scenariowise** description of $f(x, u)$.
- Our approach is first to consider strategies of **bounded variation** and then take the **lsc hull** of the the objective Ef
 - For BV strategies, stochastic integrals are given pathwise and the dual can often be written down explicitly.
 - Taking the lsc hull of Ef gives rise to stochastic integrals and it does not affect the dual problem.
 - Does require conjugation of integral functionals on spaces of stochastic processes.