Geometric and topological characterizations of strong duality in nonconvex optimization with a single equality and geometric constraints

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Talk based on a joint work with G. Cárcamo

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### Constrained Optimization

*X* real loc. conv. top. vec. sp., and  $\emptyset \neq C \subseteq X$ . Given  $f: C \to \mathbb{R}$ and  $g: C \to \mathbb{R}$ , consider the constrained minimization problem

$$
\mu \doteq \inf\{f(x): g(x) = 0, x \in C\}.
$$
 (P)

The Lagrangian dual problem associated to (*P*) is

$$
\nu \doteq \sup_{\lambda^* \in \mathbb{R}} \inf_{x \in C} [f(x) + \lambda^* g(x)]. \tag{D}
$$

We say: (P) has a (Lagrangian) *zero duality gap* if  $\mu = \nu$ ; (P) has *strong duality* if it has a zero duality gap and Problem (*D*) admits a solution.

<span id="page-2-0"></span>

### A continuous-version of SQP

$$
\mu_q = \min \Biggl\{ f(x) = \frac{1}{2} \int_0^1 x^\top(t) A x(t) dt : g(x) = \int_0^1 e^\top(t) x(t) dt - 1 = 0,
$$
  

$$
x \in C = L_+^2([0, 1[; \mathbb{R}^n]) \Biggr\}.
$$

Here,  $A = (a_{ij})$  is a real symmetric copositive matrix, i. e.,  $x^\top Ax \geq 0$  for all  $x \in \mathbb{R}^n_+$ ;  $e \in$  qi  $L^2_+(]0,1[; \mathbb{R}^n)=L^2_{++}(]0,1[; \mathbb{R}^n).$ It is known  $\{x \in L^2_+(]0,1[;{\mathbb R}^n): \; \langle e,x \rangle = 1\}$  is a weakly compact base of  $L^2_+([0,1[;\mathbb{R}^n).$  Thus, the dual is

$$
\sup_{\lambda \in \mathbb{R}} \inf_{x \in L^2_+} L(\lambda, x) = \frac{1}{2} \int_0^1 x(t)^\top Ax(t) + \lambda (\int_0^1 e(t)^\top x(t) dt - 1).
$$
\n(1)



Introduce, as usual, the Lagrangian

$$
L(\gamma, \lambda, x) = \gamma f(x) + \lambda g(x), \ \ \gamma \geq 0, \ \lambda \in \mathbb{R}.
$$

By setting  $K \doteq \{x \in C: g(x) = 0\}$ , we obtain (weak duality)

$$
\inf_{x\in C} L(\gamma,\lambda,x)\leq \inf_{x\in K} L(\gamma,\lambda,x)\leq \gamma \inf_{x\in K} f(x),\quad \forall \ \gamma\geq 0,\ \forall \ \lambda\in \mathbb{R}.
$$

In order to get the equality, we need to find conditions under which the reverse inequality holds, that is, we must have:

$$
\gamma(f(x)-\mu)+\lambda g(x)\geq 0 \quad \forall \ x\in C. \tag{2}
$$

This will imply strong duality once we get  $\gamma > 0$ . Denote  $F = (f, g)$ , the sets

$$
\mathcal{F} \doteq F(C) + \mathbb{R}_+(1,0), \ \mathcal{F}_{\mu} \doteq \mathcal{F} - \mu(1,0), \tag{3}
$$

will play an important role in our analysis.



#### Then,

$$
(\gamma, \lambda) \in [\overline{\text{cone}} \, \mathcal{F}_{\mu}]^* = [\overline{\text{cone}} \, \mathcal{F}_{\mu}]^* = [\text{cone} \, \mathcal{F}_{\mu}]^* = [\mathcal{F}_{\mu}]^*.
$$
 (4)

Set

$$
\mathcal{L}_{SD} \doteq \Big\{ \lambda \in \mathbb{R} : (1, \lambda) \in [\text{cone } \mathcal{F}_{\mu}]^* \Big\}.
$$
 (5)

Then, (P) has SD property if, and only if  $\mathcal{L}_{SD} \neq \emptyset$ . Hence

$$
\mathcal{L}_{\textit{SD}} \subseteq \mathcal{S}_{\textit{D}},
$$

where  $S_D$  is the solution set to the dual problem (*D*).



[Strong duality \(SD of order zero\)](#page-2-0) [Characterizing KKT optimality conditions \(SD or order one\)](#page-12-0)

Furthermore, we need the following numbers:

\n- \n
$$
\begin{aligned}\n \bullet \text{ if } \Omega_+^+ \doteq S_f^-(\mu) \cap S_g^+(0) \neq \emptyset, \\
s \doteq \sup_{x \in \Omega_+^-} \frac{g(x)}{f(x) - \mu} \in ]-\infty, 0]; \\
\bullet \text{ if } \Omega_-^+ \doteq S_f^-(\mu) \cap S_g^-(0) \neq \emptyset, \\
l \doteq \inf_{x \in \Omega_-^-} \frac{g(x)}{f(x) - \mu} \in [0, +\infty];\n \end{aligned}
$$
\n
\n



### The geometric and topological characterizations of SD:

Theorem: [Cárcamo-FB, 2015]

<span id="page-7-0"></span>Consider problem (*P*) with  $\mu \in \mathbb{R}$ . Then, (*a*), (*b*) and (*c*) are equivalent:

(*a*) Strong Duality holds for (*P*), that is

$$
\exists \lambda_0^* \in \mathbb{R} : f(x) + \lambda_0^* g(x) \geq \mu, \ \forall \ x \in C; \tag{6}
$$

(b) 
$$
\overline{\text{cone}}(\mathcal{F}_{\mu}) \cap (-\mathbb{R}_{++} \times \{0\}) = \emptyset
$$
 and  $\overline{\text{cone}}(\mathcal{F}_{\mu})$  is convex;

 $(c)$  cone( $\mathcal{F}_\mu$ ) is convex and exactly one of the following assertions holds:

(c1) 
$$
S_f^-(\mu) = \emptyset
$$
, in which case  $0 \in \mathcal{L}_{SD}$ ;

(c2) 
$$
\Omega^-_+ \neq \emptyset
$$
,  $s < 0$ , in which case  $\min \mathcal{L}_{SD} = -\frac{1}{s}$ ;

 $\left(\begin{matrix} c3\end{matrix}\right)$   $\Omega^- \neq \emptyset$ ,  $l > 0$ , in which case  $\max\mathcal{L}_{SD} = -\frac{1}{l}$ *l* .

#### Theorem (continued ...)

Consequently, under condition (*a*), one obtains

$$
\inf_{x \in K} f(x) = \inf_{\substack{\lambda_0^* g(x) \le 0 \\ x \in C}} f(x); \tag{7}
$$

$$
\bar{x} \text{ is a solution to } (P) \Longleftrightarrow \begin{cases} \bar{x} \in C, & g(\bar{x}) = 0, \\ f(\bar{x}) = \inf_{x \in C} [f(x) + \lambda_0^* g(x)] \end{cases}
$$
 (8)

and  $\mathcal{L}_{SD} = \mathcal{S}_{D}$ .



#### **Remark**

We point out that the convexity of  $\overline{\text{cone}}(\mathcal{F}_u)$  does imply the convexity of cone( $\mathcal{F}_{\mu}$ ) without SD. This is illustrated by the functions  $f(x_1, x_2) = 2x_1x_2$ ,  $g(x_1, x_2) = x_1$  and  $C = \mathbb{R}^2$ . Then,  $\mu=$  0,  $\mathcal{F}(\mathbb{R}^2)=\{(0,0)\}\cup(\mathbb{R}^2\setminus\mathbb{R}\times\{0\}),$  and so

$$
\mathrm{cone}(\mathcal{F}_\mu)=\mathbb{R}^2\setminus(-\mathbb{R}_{++}\times\{0\}),
$$

which is nonconvex, but  $\overline{\mathrm{cone}}(\mathcal{F}_\mu)=\mathbb{R}^2.$ 

The following result, which is new in the literature, provides a characterization of strong duality under a Slater-type condition.

#### Corollary: [Cárcamo-FB, 2015]

Let  $\mu \in \mathbb{R}$  and assume that there exist  $x_1, x_2 \in C$  such that  $g(x_1) < 0 < g(x_2)$ . Then,  $cone(\mathcal{F}_u)$  is convex if, and only if strong duality holds for (*P*).



# The case  $f$  and  $g$  quadratic:  $C = \mathbb{R}^n$ ;  $\bar{F} = (f, g)$ :

### Corollary [Opazo-FB, 2014]: Let  $\mu \in \mathbb{R}$

Assume that there exist  $x_1, x_2 \in \mathbb{R}^n$  st  $g(x_1) < 0 < g(x_2)$ . Then,  $F(\mathbb{R}^n) + \mathbb{R}_+(1,0)$  is convex if, and only if SD holds.

### Lemma [Opazo-FB, 2014]:

 $F(\mathbb{R}^n) + \mathbb{R}_+(1,0)$  is convex if, and only if any of the following conditions is satisfied:

(C1) 
$$
F_L(\ker A \cap \ker B) \neq \{0\}; F_L(u) = (\langle a, u \rangle, \langle b, u \rangle);
$$

 $(C2)$   $B \neq 0$ ;

(C3) 
$$
u \in \mathbb{R}^n
$$
,  $\langle Bu, u \rangle = 0 \Longrightarrow \langle Au, u \rangle \ge 0$ ;

$$
(C4) \ \exists u \in \mathbb{R}^n, \ \langle Au, u \rangle < 0, \ \langle Bu, u \rangle = 0, \ \langle b, u \rangle = 0.
$$

This characterization encompasses the case when the Hessian of *g* is non-null, or when *g* is strictly concave (or convex). [Characterizing strong duality](#page-0-0)



### Corollary [Opazo-FB, 2014]:

 $F(\mathbb{R}^n) + P$  is convex for all convex cone  $P \subseteq \mathbb{R}^2$  with int  $P \neq \emptyset$ .

FLORES-BAZÁN, F.; OPAZO, FELIPE, Joint-range convexity for a pair of inhomogeneous quadratic functions and a nonstrict version of S-lemma with equality, *Submitted*.



# **KKT** optimality conditions

This section deals with some characterizations of the validity of the KKT optimality conditions for the problem (*P*). For simplicity, take  $X = \mathbb{R}^n$ , and  $f$  and  $g$  to be Gâteaux differentiable on  $\mathbb{R}^n$ . Such characterizations will be derived as a consequence of our main theorem on SD applied to the linearized approximation problem defined, given  $\bar{x} \in C$ , by

<span id="page-12-1"></span>
$$
\mu_L \doteq \inf_{\mathsf{v}\in G'(\bar{\mathsf{x}})} \nabla f(\bar{\mathsf{x}})^\top \mathsf{v},\tag{9}
$$

where

$$
G'(\bar{x}) \doteq \Big\{ v \in \mathcal{T}(C; \bar{x}) : \nabla g(\bar{x})^{\top} v = 0 \Big\}.
$$

Here,  $T(C; \bar{x})$  stands for the contingent cone of C (or tangent cone of Bouligand) at  $\bar{x}$ , which is always a closed cone. Set  $F_L(v) = (\nabla f(\bar{x})^\top v, \nabla g(\bar{x})^\top v)$ . It is obvious that  $\mu_L \in \{-\infty, 0\}$ .

<span id="page-12-0"></span>

In view of Theorem [8,](#page-7-0) we introduce the following sets:

$$
\widehat{S}_f^-(0) \doteq \{v \in \mathcal{T}(\mathcal{C};\bar{x}): \; \nabla f(\bar{x})^\top v < 0\},
$$

$$
\widehat{S}_g^+(0) = \{v \in \mathcal{T}(C;\bar{x}): \nabla g(\bar{x})^\top v > 0\},\
$$

$$
\widehat{\Omega}^-_+ \doteq \widehat{S}^-_f(0) \cap \widehat{S}^+_g(0), \ \ \widehat{\Omega}^-_- \doteq \widehat{S}^-_f(0) \cap \widehat{S}^-_g(0).
$$

Furthermore, whenever  $\widehat{\Omega}^-_+ \neq \emptyset \neq \widehat{\Omega}^-_-$ , we put

$$
\widehat{s} \doteq \sup_{v \in \widehat{\Omega}_+} \frac{\nabla g(\bar{x})^\top v}{\nabla f(\bar{x})^\top v}, \quad \widehat{l} \doteq \inf_{v \in \widehat{\Omega}_-} \frac{\nabla g(\bar{x})^\top v}{\nabla f(\bar{x})^\top v}.
$$

Denote by  $\mathcal{L}(\bar{x})$  the set of Lagrange multipliers to  $(P)$ associated to a (not necessarily feasible) point  $\bar{x} \in C$ , i. e., the set of  $\lambda^* \in \mathbb{R}$  satisfying [\(10\)](#page-14-0). When  $\mathcal{L}(\bar{x}) \neq \emptyset$ , we say that  $\bar{x}$  is a KKT point.



[Strong duality \(SD of order zero\)](#page-2-0) [Characterizing KKT optimality conditions \(SD or order one\)](#page-12-0)

Let  $\bar{x} \in C$ . In case  $\nabla g(\bar{x}) = 0$ , it is not difficult to check that:

- $\bullet$   $\mu_l = 0$  if, and only if  $\mathcal{L}(\bar{x}) = \mathbb{R}$ .
- $\mu_I = -\infty$  if, and only if  $\mathcal{L}(\bar{x}) = \emptyset$ .

#### Theorem: [Cárcamo-FB, 2015]

Assume that  $\bar{x} \in C$ . The following assertions are equivalent:  $(a) \exists \lambda^* \in \mathbb{R}$  such that

<span id="page-14-0"></span>
$$
\nabla f(\bar{x}) + \lambda^* \nabla g(\bar{x}) \in [T(C; \bar{x})]^*.
$$
 (10)

(b)  $\mu_l = 0$  and strong duality holds for the problem [\(9\)](#page-12-1).  $(c)$   $\overline{F_1(T(C;\bar{x}))+\mathbb{R}_+(1,0)}$  is convex and

$$
\overline{[F_L(T(C;\bar{x}))+\mathbb{R}_+(1,0)]}\cap(-\mathbb{R}_{++}\times\{0\})=\emptyset.
$$
 (11)



#### Theorem (continued ...)

 $(d)$   $F_L(T(C;\bar{x})) + \mathbb{R}_+(1,0)$  is convex and exactly one of the following assertions holds:  $(d1)$   $\hat{S}_f^-(0) = \emptyset$ , in which case  $0 \in \mathcal{L}(\bar{x});$  $(d2)$   $\widehat{\Omega}^-_+ \neq \emptyset$ ,  $\widehat{s} < 0$ , in which case  $\min \mathcal{L}(\bar{x}) = -\frac{1}{\widehat{s}}$ b*s* ;  $(d3)$   $\widehat{\Omega}^-$  ≠  $\emptyset$ ,  $\widehat{l}$  > 0, in which case max $\mathcal{L}(\bar{x}) = -\frac{1}{\widehat{l}}$ b*l* . (*e*)  $\overline{F_1(T(C;\bar{x}))} + \mathbb{R}_+(1,0)$  is convex,  $\mu_1 = 0$  and  $v_k \in \mathcal{T}(C; \bar{x}), ||v_k|| \rightarrow +\infty,$  $\nabla g(\bar{\pmb{x}})^\top \pmb{\mathsf{v}}_k \to \pmb{0}, \nabla f(\bar{\pmb{x}})^\top \pmb{\mathsf{v}}_k < \pmb{0}]$  $\left\{\Rightarrow \frac{}{\overline{\lim_{k\rightarrow}}\nabla f(\bar{\mathbf{x}})^\top \mathbf{v}_k = \mathbf{0}.} \right\}$ (12)



A simple sufficient condition for a minimum to be a KKT point, under strong duality is expressed in the following result.

#### Proposition [Cárcamo-FB, 2015]:

Assume that strong duality holds for (*P*). Then, every solution to  $(P)$  is a KKT point, that is,  $\mathcal{L}_{SD} \subseteq \mathcal{L}(\bar{X})$  for all  $\bar{x} \in \mathrm{argmin}\; f.$ *K*

It may applied to situations where results based either on exact penalization techniques ([Yang-Peng, MOR 2007]) or where Abadie's constraint qualification fail. In addition, there are instances where no minimizer is a KKT point, if strong duality is not satisfied. For 1st case:

$$
0 = \mu = \min\{f(x_1, x_2) = x_2 : g(x_1, x_2) = x_2 - x_1^2 = 0, (x_1, x_2) \in \mathbb{R}^2\}.
$$
  
For 2nd case:  $f(x_1, x_2) = x_2$ ,  $g(x_1, x_2) = (x_1 - 1)^2 + (x_2 - 1)^2 - 1$   
and  $C = \{(x_1, x_2) \in \mathbb{R}^2 : g_0(x_1, x_2) \le 0\}$  with  
 $g_0(x_1, x_2) = (x_1 - 1)^2 + (x_2 + 1)^2 - 1.$ 

### Nonconvex QP with two quadratic equality constraints

We now discuss the problem:

<span id="page-17-0"></span>
$$
\mu = \min\{f(x): g_1(x) = 0, g_2(x) = 0\},
$$
 (13)

where we specialize the functions  $f,g_i,\,i=1,2$  to be (non necessarily homogeneous) quadratic. Here,  $C = \{x \in \mathbb{R}^n : g_2(x) = 0\}, K = \{x \in C : g_1(x) = 0\},\$ 

$$
f(x) \doteq \frac{1}{2}x^\top Ax + a^\top x + \alpha, \ \ g_i(x) \doteq \frac{1}{2}x^\top B_i x + b_i^\top x + \beta_i, \ \ i = 1, 2,
$$

with  $A = A^{\top}, B_i = B_i^{\top}$ ;  $a, b_i \in \mathbb{R}^n$  and  $\alpha, \beta_i$  being real numbers. In addition to the dual problem

$$
\nu \doteq \sup_{\lambda_1 \in \mathbb{R}} \inf_{x \in C} \{f(x) + \lambda_1 g_1(x)\},\tag{14}
$$

consider also the standard (Lagrangian) dual problem to [\(13\)](#page-17-0):

<span id="page-18-0"></span>
$$
\nu_0 \doteq \sup_{\lambda_1, \lambda_2 \in \mathbb{R}} \inf_{x \in \mathbb{R}^n} \{f(x) + \lambda_1 g_1(x) + \lambda_2 g_2(x)\}.
$$
 (15)

We say that problem [\(13\)](#page-17-0) has standard strong duality (SSD) if  $\mu = \nu_0$  and problem [\(15\)](#page-18-0) admits solution. It is easy to check that

$$
\nu_0\leq \nu\leq \mu.
$$

One the other hand, given a feasible point  $\bar{x}$ , it is said that  $\bar{x}$  is a standard KKT point to problem [\(13\)](#page-17-0), if for some  $\lambda_1, \lambda_2 \in \mathbb{R}$ , one has

$$
\nabla f(\bar{x}) + \lambda_1 \nabla g_1(\bar{x}) + \lambda_2 \nabla g_2(\bar{x}) = 0.
$$



Set

$$
Z(\bar{x})\doteq \{v\in\mathbb{R}^n:\ \nabla g_i(\bar{x})^\top v+\frac{1}{2}v^\top B_i v=0,\ \ i=1,2\}.
$$

It is known that

$$
\mathcal{T}(C;\bar{x})=\left\{\boldsymbol{v}\in\mathbb{R}^n:\;\nabla g_2(\bar{x})^\top\boldsymbol{v}=0\;\right\}=\nabla g_2(\bar{x})^\perp\;\textrm{if}\;\nabla g_2(\bar{x})\neq 0,
$$

and so  $[T(C; \bar{x})]^{*} = \mathbb{R} \nabla g_{2}(\bar{x})$ ; whereas

$$
\mathcal{T}(C;\bar{x})=\Big\{v\in\mathbb{R}^n:\;v^\top B_2v=0\;\Big\}\;\;\text{if}\;\;\nabla g_2(\bar{x})=0.
$$

The latter set is, in general, nonconvex. However, in case  $B_2$  is positive semidefinite, or equivalently,  $g_2$  is convex (for instance, when such an equality constraint corresponds to a component of x taking the value either 0 or 1), with  $\nabla g_2(\bar{x}) = 0$ , we obtain  $T(C; \bar{x}) = \text{ker } B_2$ , and so  $[T(C; \bar{x})]^* = (\text{ker } B_2)^{\perp} = B_2(\mathbb{R}^n)$ .



Next theorem, which is new, provides 1st and 2nd order necessary optimality conditions under additional assumptions besides SD. It proves that every optimal solution is a standard KKT point.

#### Theorem [Cárcamo-FB, 2015]: Let  $\mu\in\mathbb{R}$

Let *f*,  $g_1, g_2$  be quadratic,  $\bar{x}$  feasible satisfying  $\nabla g_2(\bar{x}) \neq 0$ . Set  $C = \{x \in \mathbb{R}^n : g_2(x) = 0\}$ . Then  $(a) \Longrightarrow (b)$ , where (a)  $\bar{x}$  is a solution to [\(13\)](#page-17-0) and SD holds;  $(b) \exists \lambda_1, \lambda_2 \in \mathbb{R}$  such that  $\nabla f(\bar{x}) + \lambda_1 \nabla g_1(\bar{x}) + \lambda_2 \nabla g_2(\bar{x}) = 0$ ,  $A + \lambda_1 B_1 + \lambda_2 B_2 \succcurlyeq 0$  on  $Z_2(\bar{x}) \cup \nabla g_2(\bar{x})^{\perp}$ .

It may be applied to instances without satisfying Abadie's CQ.

$$
Z_2(\bar{x})\doteq \{\boldsymbol{v}\in\mathbb{R}^n:\ \nabla g_2(\bar{x})^\top \boldsymbol{v}+\frac{1}{2}\boldsymbol{v}^\top B_2 \boldsymbol{v}=0\}.
$$



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### A concrete application

$$
\mu_q = \min \Biggl\{ f(x) = \frac{1}{2} \int_0^1 x^\top(t) A x(t) dt : g(x) = \int_0^1 e^\top(t) x(t) dt - 1 = 0, \\ x \in C \doteq L_+^2([0, 1]; \mathbb{R}^n) \Biggr\}.
$$

 $\textsf{Here, } e \in \text{qi } L^2_+([0,1[;\mathbb{R}^n) = L^2_{++}([0,1[;\mathbb{R}^n) \text{.\ } \textsf{F} = (f,g) \text{.}$ 

### Proposition: Assume  $\mu_q > 0$ ,

\n- (a) 
$$
\Omega_{+}^{-} = \Omega_{+}^{-} = \emptyset
$$
, and therefore  $S_g^+(0) = \Omega_{+}^+ \neq \emptyset$ ;
\n- (b)  $\emptyset \neq S_f^-(\mu_q) = \Omega_{-}^{-}$ ;
\n- (c)  $m = I = \frac{1}{2\mu_q}$ , so  $I > 0$  and  $\mathcal{L}_{SD} = \mathcal{S}_D = \{-2\mu_q\}$ , and so  $\text{cone}(F(C) + \mathbb{R}_+(1, 0) - \mu_q(1, 0)) = \left\{(u, v) : v \leq \frac{1}{2\mu_q}u\right\}$ ;
\n- (d) strong duality holds.
\n

[Strong duality \(SD of order zero\)](#page-2-0) [Characterizing KKT optimality conditions \(SD or order one\)](#page-12-0)

By Lyapunov theorem  $F(C) + \mathbb{R}_+(1,0)$  is convex.

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